## **SIEMENS**

Data sheet 3RW5546-2HA04



SIRIUS soft starter 200-480 V 370 A, 24 V AC/DC spring-type terminals

product brand name	SIRIUS
product category	Hybrid switching devices
product designation	Soft starter
product type designation	3RW55
manufacturer's article number	
<ul> <li>of high feature HMI module usable</li> </ul>	3RW5980-0HF00
<ul> <li>of communication module PROFINET standard usable</li> </ul>	3RW5980-0CS00
<ul> <li>of communication module PROFINET high-feature usable</li> </ul>	3RW5950-0CH00
<ul> <li>of communication module PROFIBUS usable</li> </ul>	3RW5980-0CP00
<ul> <li>of communication module Modbus TCP usable</li> </ul>	3RW5980-0CT00
<ul> <li>of communication module Modbus RTU usable</li> </ul>	3RW5980-0CR00
<ul> <li>of communication module Ethernet/IP</li> </ul>	3RW5980-0CE00
<ul> <li>of circuit breaker usable at 400 V</li> </ul>	3VA2440-7MN32-0AA0; Type of coordination 1, Iq = 65 kA, CLASS 10
<ul> <li>of circuit breaker usable at 500 V</li> </ul>	3VA2440-7MN32-0AA0; Type of coordination 1, Iq = 65 kA, CLASS 10
<ul> <li>of circuit breaker usable at 400 V at inside-delta circuit</li> </ul>	3VA2580-6HN32-0AA0; Type of coordination 1, Iq = 65 kA, CLASS 10
<ul> <li>of circuit breaker usable at 500 V at inside-delta circuit</li> </ul>	3VA2580-6HN32-0AA0; Type of coordination 1, Iq = 65 kA, CLASS 10
<ul> <li>of the gG fuse usable up to 690 V</li> </ul>	2x3NA3365-6; Type of coordination 1, Iq = 65 kA
<ul> <li>of the gG fuse usable at inside-delta circuit up to 500 V</li> </ul>	2x3NA3365-6; Type of coordination 1, Iq = 65 kA
<ul> <li>of full range R fuse link for semiconductor protection usable up to 690 V</li> </ul>	3NE1334-2; Type of coordination 2, Iq = 65 kA

General technical data	
starting voltage [%]	20 100 %
stopping voltage [%]	50 50 %
start-up ramp time of soft starter	0 360 s
ramp-down time of soft starter	0 360 s
start torque [%]	10 100 %
stopping torque [%]	10 100 %
torque limitation [%]	20 200 %
current limiting value [%] adjustable	125 800 %
breakaway voltage [%] adjustable	40 100 %
breakaway time adjustable	0 2 s
number of parameter sets	3
accuracy class acc. to IEC 61557-12	5 %
certificate of suitability	

CE marking	Yes
UL approval	Yes
CSA approval	Yes
product component	103
HMI-High Feature	Yes
is supported HMI-High Feature	Yes
product feature integrated bypass contact system	Yes
number of controlled phases	3
trip class	CLASS 10A / 10E (default) / 20E / 30E; acc. to IEC 60947-4-2
current unbalance limiting value [%]	10 60 %
ground-fault monitoring limiting value [%]	10 95 %
buffering time in the event of power failure	
• for main current circuit	100 ms
• for control circuit	100 ms
idle time adjustable	0 255 s
insulation voltage rated value	480 V
degree of pollution	3, acc. to IEC 60947-4-2
impulse voltage rated value	6 kV
blocking voltage of the thyristor maximum	1 400 V
service factor	1.15
surge voltage resistance rated value	6 kV
maximum permissible voltage for safe isolation	
between main and auxiliary circuit	480 V; does not apply for thermistor connection
shock resistance	15 g / 11 ms, from 6 g / 11 ms with potential contact lifting
vibration resistance	15 mm up to 6 Hz; 2 g up to 500 Hz
recovery time after overload trip adjustable	60 1 800 s
utilization category acc. to IEC 60947-4-2	AC 53a
reference code acc. to IEC 81346-2	Q
Substance Prohibitance (Date)	15.02.2018 00:00:00
product function	
<ul><li>ramp-up (soft starting)</li></ul>	Yes
<ul><li>ramp-down (soft stop)</li></ul>	Yes
<ul><li>breakaway pulse</li></ul>	Yes
<ul> <li>adjustable current limitation</li> </ul>	Yes
<ul> <li>creep speed in both directions of rotation</li> </ul>	Voc
- creep speed in both directions of foldtion	Yes
pump ramp down	Yes
• pump ramp down	Yes
<ul><li>pump ramp down</li><li>DC braking</li></ul>	Yes Yes
<ul><li>pump ramp down</li><li>DC braking</li><li>motor heating</li></ul>	Yes Yes Yes
<ul> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> </ul>	Yes Yes Yes Yes
<ul> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> </ul>	Yes Yes Yes Yes Yes
<ul> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> </ul>	Yes
<ul> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> </ul>	Yes
<ul> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes; Full motor protection (thermistor motor protection and electronic motor overload protection) / When using the motor overload protection according to ATEX, an upstream contactor is required in inside-delta circuit. Yes; Type A PTC or Klixon / Thermoclick
<ul> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> <li>inside-delta circuit</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes; Full motor protection (thermistor motor protection and electronic motor overload protection) / When using the motor overload protection according to ATEX, an upstream contactor is required in inside-delta circuit. Yes; Type A PTC or Klixon / Thermoclick Yes
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<ul> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>manual RESET</li> <li>remote reset</li> <li>communication function</li> <li>operating measured value display</li> </ul>	Yes Yes Yes Yes Yes Yes Yes; Full motor protection (thermistor motor protection and electronic motor overload protection) / When using the motor overload protection according to ATEX, an upstream contactor is required in inside-delta circuit. Yes; Type A PTC or Klixon / Thermoclick Yes Yes Yes Yes Yes Yes Yes
<ul> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>manual RESET</li> <li>remote reset</li> <li>communication function</li> <li>operating measured value display</li> <li>event list</li> </ul>	Yes Yes Yes Yes Yes Yes Yes; Full motor protection (thermistor motor protection and electronic motor overload protection) / When using the motor overload protection according to ATEX, an upstream contactor is required in inside-delta circuit. Yes; Type A PTC or Klixon / Thermoclick Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>manual RESET</li> <li>remote reset</li> <li>communication function</li> <li>operating measured value display</li> <li>event list</li> <li>error logbook</li> </ul>	Yes Yes Yes Yes Yes Yes Yes; Full motor protection (thermistor motor protection and electronic motor overload protection) / When using the motor overload protection according to ATEX, an upstream contactor is required in inside-delta circuit.  Yes; Type A PTC or Klixon / Thermoclick Yes
<ul> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>manual RESET</li> <li>remote reset</li> <li>communication function</li> <li>operating measured value display</li> <li>event list</li> <li>error logbook</li> <li>via software parameterizable</li> </ul>	Yes Yes Yes Yes Yes Yes Yes; Full motor protection (thermistor motor protection and electronic motor overload protection) / When using the motor overload protection according to ATEX, an upstream contactor is required in inside-delta circuit.  Yes; Type A PTC or Klixon / Thermoclick Yes
<ul> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>manual RESET</li> <li>remote reset</li> <li>communication function</li> <li>operating measured value display</li> <li>event list</li> <li>error logbook</li> <li>via software parameterizable</li> <li>via software configurable</li> </ul>	Yes Yes Yes Yes Yes Yes; Full motor protection (thermistor motor protection and electronic motor overload protection) / When using the motor overload protection according to ATEX, an upstream contactor is required in inside-delta circuit. Yes; Type A PTC or Klixon / Thermoclick Yes
<ul> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>manual RESET</li> <li>remote reset</li> <li>communication function</li> <li>operating measured value display</li> <li>event list</li> <li>error logbook</li> <li>via software parameterizable</li> <li>via software configurable</li> <li>screw terminal</li> </ul>	Yes Yes Yes Yes Yes Yes Yes; Full motor protection (thermistor motor protection and electronic motor overload protection) / When using the motor overload protection according to ATEX, an upstream contactor is required in inside-delta circuit. Yes; Type A PTC or Klixon / Thermoclick Yes

	Feature communication modules
• firmware update	Yes
removable terminal for control circuit	Yes
voltage ramp	Yes
torque control	Yes
combined braking	Yes
analog output	Yes; 4 20 mA (default) / 0 10 V
programmable control inputs/outputs	Yes
condition monitoring	Yes
automatic parameterisation	Yes
application wizards	Yes
alternative run-down	Yes
emergency operation mode	Yes
reversing operation	Yes
<ul> <li>soft starting at heavy starting conditions</li> </ul>	Yes
Power Electronics	
operational current	
at 40 °C rated value	370 A
<ul> <li>at 40 °C rated value minimum</li> </ul>	74 A
• at 50 °C rated value	328 A
• at 60 °C rated value	300 A
operational current at inside-delta circuit	
<ul> <li>at 40 °C rated value</li> </ul>	641 A
<ul> <li>at 50 °C rated value</li> </ul>	568 A
at 60 °C rated value	519 A
operating voltage	
rated value	200 480 V
at inside-delta circuit rated value	200 480 V
relative negative tolerance of the operating voltage	-15 %
relative positive tolerance of the operating voltage	10 %
relative negative tolerance of the operating voltage at inside-delta circuit	-15 %
relative positive tolerance of the operating voltage at inside-delta circuit	10 %
	10 %
inside-delta circuit	10 %
inside-delta circuit operating power for 3-phase motors	
inside-delta circuit operating power for 3-phase motors • at 230 V at 40 °C rated value	110 kW 200 kW 200 kW
inside-delta circuit operating power for 3-phase motors  • at 230 V at 40 °C rated value • at 230 V at inside-delta circuit at 40 °C rated value • at 400 V at 40 °C rated value • at 400 V at inside-delta circuit at 40 °C rated value	110 kW 200 kW 200 kW 355 kW
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value	110 kW 200 kW 200 kW 355 kW
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value	110 kW 200 kW 200 kW 355 kW 50 Hz
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 %
inside-delta circuit operating power for 3-phase motors  • at 230 V at 40 °C rated value • at 230 V at inside-delta circuit at 40 °C rated value • at 400 V at 40 °C rated value • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 %
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%]	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 %
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%]  power loss [W] for rated value of the current at AC	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 %; Relative to set le
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%]  power loss [W] for rated value of the current at AC  • at 40 °C after startup	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%]  power loss [W] for rated value of the current at AC  • at 40 °C after startup  • at 50 °C after startup	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%]  power loss [W] for rated value of the current at AC  • at 40 °C after startup  • at 50 °C after startup  • at 60 °C after startup	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%]  power loss [W] for rated value of the current at AC  • at 40 °C after startup  • at 50 °C after startup  • at 60 °C after startup  power loss [W] at AC at current limitation 350 %	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le  111 W 98 W 90 W
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency  relative positive tolerance of the operating frequency  minimum load [%]  power loss [W] for rated value of the current at AC  • at 40 °C after startup  • at 50 °C after startup  • at 60 °C after startup  power loss [W] at AC at current limitation 350 %  • at 40 °C during startup	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le  111 W 98 W 90 W
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency  relative positive tolerance of the operating frequency  minimum load [%]  power loss [W] for rated value of the current at AC  • at 40 °C after startup  • at 50 °C after startup  power loss [W] at AC at current limitation 350 %  • at 40 °C during startup  • at 50 °C during startup	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le  111 W 98 W 90 W  5 563 W 4 694 W
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%]  power loss [W] for rated value of the current at AC  • at 40 °C after startup  • at 50 °C after startup  power loss [W] at AC at current limitation 350 %  • at 40 °C during startup  • at 50 °C during startup  • at 60 °C during startup	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le  111 W 98 W 90 W  5 563 W 4 694 W 4 145 W
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency  relative positive tolerance of the operating frequency  minimum load [%]  power loss [W] for rated value of the current at AC  • at 40 °C after startup  • at 50 °C after startup  power loss [W] at AC at current limitation 350 %  • at 40 °C during startup  • at 50 °C during startup  • at 60 °C during startup  type of the motor protection	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le  111 W 98 W 90 W  5 563 W 4 694 W
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value • at 230 V at inside-delta circuit at 40 °C rated value • at 400 V at 40 °C rated value • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%]  power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup  power loss [W] at AC at current limitation 350 % • at 40 °C during startup • at 50 °C during startup • at 60 °C during startup  output  type of the motor protection  Control circuit/ Control	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le  111 W 98 W 90 W  5 563 W 4 694 W 4 145 W Electronic, tripping in the event of thermal overload of the motor
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%]  power loss [W] for rated value of the current at AC  • at 40 °C after startup  • at 50 °C after startup  power loss [W] at AC at current limitation 350 %  • at 40 °C during startup  • at 50 °C during startup  • at 60 °C during startup  type of the motor protection  Control circuit/ Control  type of voltage of the control supply voltage	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le  111 W 98 W 90 W  5 563 W 4 694 W 4 145 W
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value • at 230 V at inside-delta circuit at 40 °C rated value • at 400 V at 40 °C rated value • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%]  power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup  power loss [W] at AC at current limitation 350 % • at 40 °C during startup • at 50 °C during startup • at 60 °C during startup  output  type of the motor protection  Control circuit/ Control	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le  111 W 98 W 90 W  5 563 W 4 694 W 4 145 W Electronic, tripping in the event of thermal overload of the motor
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%]  power loss [W] for rated value of the current at AC  • at 40 °C after startup  • at 50 °C after startup  power loss [W] at AC at current limitation 350 %  • at 40 °C during startup  • at 50 °C during startup  type of the motor protection  Control circuit/ Control  type of voltage of the control supply voltage control supply voltage at AC	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le  111 W 98 W 90 W  5 563 W 4 694 W 4 145 W Electronic, tripping in the event of thermal overload of the motor
inside-delta circuit  operating power for 3-phase motors  • at 230 V at 40 °C rated value  • at 230 V at inside-delta circuit at 40 °C rated value  • at 400 V at 40 °C rated value  • at 400 V at inside-delta circuit at 40 °C rated value  Operating frequency 1 rated value  Operating frequency 2 rated value  relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%]  power loss [W] for rated value of the current at AC  • at 40 °C after startup  • at 50 °C after startup  power loss [W] at AC at current limitation 350 %  • at 40 °C during startup  • at 50 °C during startup  • at 60 °C during startup  type of the motor protection  Control circuit/ Control  type of voltage of the control supply voltage control supply voltage at AC  • at 50 Hz rated value	110 kW 200 kW 200 kW 355 kW 50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le  111 W 98 W 90 W  5 563 W 4 694 W 4 145 W Electronic, tripping in the event of thermal overload of the motor  AC/DC

voltage at AC at 50 Hz	
relative positive tolerance of the control supply voltage at AC at 50 Hz	20 %
relative negative tolerance of the control supply voltage at AC at 60 Hz	-20 %
relative positive tolerance of the control supply voltage at AC at 60 Hz	20 %
control supply voltage frequency	50 60 Hz
relative negative tolerance of the control supply voltage frequency	-10 %
relative positive tolerance of the control supply voltage frequency	10 %
control supply voltage	
at DC rated value	24 V
relative negative tolerance of the control supply voltage at DC	-20 %
relative positive tolerance of the control supply voltage at DC	20 %
control supply current in standby mode rated value	440 mA
holding current in bypass operation rated value	720 mA
locked-rotor current at close of bypass contact maximum	6.7 A
inrush current peak at application of control supply voltage maximum	7.5 A
duration of inrush current peak at application of control supply voltage	20 ms
design of the overvoltage protection	Varistor
design of short-circuit protection for control circuit	4 A gG fuse (Icu=1 kA), 6 A quick-acting fuse (Icu=1 kA), C1 miniature circuit breaker (Icu= 600 A), C6 miniature circuit breaker (Icu= 300 A); Is not part of scope of supply
nputs/ Outputs	
number of digital inputs	4
<ul> <li>parameterizable</li> </ul>	4
number of inputs for thermistor connection	1; Type A PTC or Klixon / Thermoclick
<ul> <li>number of digital outputs</li> </ul>	4
<ul> <li>number of digital outputs parameterizable</li> </ul>	3
<ul> <li>number of digital outputs not parameterizable</li> </ul>	1
digital output version	3 normally-open contacts (NO) / 1 changeover contact (CO)
number of analog outputs	1
switching capacity current of the relay outputs	
<ul><li>at AC-15 at 250 V rated value</li></ul>	3 A
<ul> <li>at DC-13 at 24 V rated value</li> </ul>	37
at Bo To at 24 v Tated value	1A
nstallation/ mounting/ dimensions	
nstallation/ mounting/ dimensions	1 A
nstallation/ mounting/ dimensions mounting position	1 A  Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°)
nstallation/ mounting/ dimensions mounting position fastening method	1 A  Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing
nstallation/ mounting/ dimensions mounting position fastening method height	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 393 mm
nstallation/ mounting/ dimensions mounting position fastening method height width	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 393 mm 210 mm
mounting position fastening method height width depth required spacing with side-by-side mounting • forwards	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 393 mm 210 mm 203 mm
mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 393 mm 210 mm 203 mm
mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 393 mm 210 mm 203 mm  10 mm 0 mm 100 mm
mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • downwards	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 393 mm 210 mm 203 mm  10 mm 0 mm 100 mm
mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • downwards • at the side	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 393 mm 210 mm 203 mm  10 mm 10 mm 100 mm 75 mm 5 mm
mounting position fastening method height width depth required spacing with side-by-side mounting  • forwards • backwards • upwards • downwards • at the side weight without packaging	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 393 mm 210 mm 203 mm  10 mm 0 mm 100 mm
mounting position fastening method height width depth required spacing with side-by-side mounting	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 393 mm 210 mm 203 mm  10 mm 10 mm 100 mm 75 mm 5 mm
mounting position fastening method height width depth required spacing with side-by-side mounting	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 393 mm 210 mm 203 mm  10 mm 0 mm 100 mm 75 mm 5 mm 10.9 kg
mounting position  fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • downwards • at the side  weight without packaging  Connections/ Terminals  type of electrical connection • for main current circuit	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 393 mm 210 mm 203 mm  10 mm 0 mm 100 mm 75 mm 5 mm 10.9 kg
mounting position fastening method height width depth required spacing with side-by-side mounting	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 393 mm 210 mm 203 mm  10 mm 0 mm 100 mm 75 mm 5 mm 10.9 kg

with conductor cross section = 0.5 mm² mayimum	F0 m
with conductor cross-section = 0.5 mm² maximum      with conductor cross-section = 4.5 mm² maximum	50 m
with conductor cross-section = 1.5 mm² maximum      with conductor cross-section = 2.5 mm² maximum	150 m 250 m
with conductor cross-section = 2.5 mm² maximum  type of connectable conductor cross-sections	250 111
· ·	2v /F0 240 mm²\
for DIN cable lug for main contacts stranded     for DIN cable lug for main contacts finely stranded	2x (50 240 mm²) 2x (70 240 mm²)
for DIN cable lug for main contacts finely stranded  type of connectable conductor cross-sections	2x (10 240 IIIII <sup>-</sup> )
for control circuit solid	2x (0.25 1.5 mm²)
for control circuit solid     for control circuit finely stranded with core end	·
processing	2x (0.25 1.5 mm²)
at AWG cables for control circuit solid	2x (24 16)
<ul> <li>at AWG cables for control circuit finely stranded with</li> </ul>	2x (24 16)
core end processing	
wire length	
<ul> <li>between soft starter and motor maximum</li> </ul>	800 m
at the digital inputs at DC maximum	1 000 m
tightening torque	
<ul> <li>for main contacts with screw-type terminals</li> </ul>	14 24 N·m
for auxiliary and control contacts with screw-type	0.8 1.2 N·m
terminals	
tightening torque [lbf·in]	404 240 lbf in
for main contacts with screw-type terminals	124 210 lbf·in
<ul> <li>for auxiliary and control contacts with screw-type terminals</li> </ul>	7 10.3 lbf·in
Ambient conditions	
installation altitude at height above sea level maximum	5 000 m; Derating as of 1000 m, see catalog
ambient temperature	o ooo m, beraang as or roos m, see satalog
during operation	-25 +60 °C; Please observe derating at temperatures of 40 °C or
- daming operation	above
<ul> <li>during storage and transport</li> </ul>	-40 +80 °C
environmental category	
<ul> <li>during operation acc. to IEC 60721</li> </ul>	3K6 (no ice formation, only occasional condensation), 3C3 (no salt
	mist), 3S2 (sand must not get into the devices), 3M6
<ul> <li>during storage acc. to IEC 60721</li> </ul>	1K6 (only occasional condensation), 1C2 (no salt mist), 1S2 (sand must not get inside the devices), 1M4
<ul> <li>during transport acc. to IEC 60721</li> </ul>	2K2, 2C1, 2S1, 2M2 (max. fall height 0.3 m)
EMC emitted interference	acc. to IEC 60947-4-2: Class A
Communication/ Protocol	330.10.120.000.11.1.21.01330.11
communication module is supported	
PROFINET standard	Yes
PROFINET standard     PROFINET high-feature	Yes
• EtherNet/IP	Yes
Modbus RTU	Yes
Modbus TCP	Yes
PROFIBUS	Yes
UL/CSA ratings	
manufacturer's article number	
of the fuse	
usable for Standard Faults up to 575/600 V     according to UL	Type: Class J / L, max. 1200 A; lq = 18 kA
— usable for High Faults up to 575/600 V	Type: Class J / L, max. 1200 A; Iq = 100 kA
according to UL  — usable for Standard Faults at inside-delta	Type: Class J / L, max. 1200 A; Iq = 18 kA
circuit up to 575/600 V according to UL  — usable for High Faults at inside-delta circuit up	Type: Class J / L, max. 1200 A; lq = 100 kA
to 575/600 V according to UL	
operating power [hp] for 3-phase motors	100 hp
• at 200/208 V at 50 °C rated value	100 hp
• at 220/230 V at 50 °C rated value	125 hp
at 460/480 V at 50 °C rated value     at 200/208 V at incide delta sircuit at 50 °C rated	250 hp
<ul> <li>at 200/208 V at inside-delta circuit at 50 °C rated</li> </ul>	200 hp

value	
<ul> <li>at 220/230 V at inside-delta circuit at 50 °C rated value</li> </ul>	200 hp
• at 460/480 V at inside-delta circuit at 50 °C rated value	450 hp
contact rating of auxiliary contacts according to UL	R300-B300
Safety related data	
protection class IP on the front acc. to IEC 60529	IP00; IP20 with cover
touch protection on the front acc. to IEC 60529	finger-safe, for vertical contact from the front with cover
electromagnetic compatibility	acc. to IEC 60947-4-2
ATEX	
certificate of suitability	
• ATEX	Yes
• IECEx	Yes
<ul> <li>according to ATEX directive 2014/34/EU</li> </ul>	BVS 18 ATEX F 003 X
type of protection according to ATEX directive 2014/34/EU	II (2)G [Ex eb Gb] [Ex db Gb] [Ex pxb Gb], II (2)D [Ex tb Db] [Ex pxb Db], I (M2) [Ex db Mb]
hardware fault tolerance acc. to IEC 61508 relating to ATEX	0
PFDavg with low demand rate acc. to IEC 61508 relating to ATEX	0.008
PFHD with high demand rate acc. to EN 62061 relating to ATEX	0.0000005 1/h
Safety Integrity Level (SIL) acc. to IEC 61508 relating to ATEX	SIL1
T1 value for proof test interval or service life acc. to IEC 61508 relating to ATEX	3 y

Certificates/ approvals

**General Product Approval** 

**EMC** 

For use in hazardous locations













For use in hazardous locations **Declaration of Conformity** 

**Test Certificates** 

Marine / Shipping





Type Test Certificates/Test Report







Marine / Shipping

other





Confirmation

## Further information

Information- and Downloadcenter (Catalogs, Brochures,...)

https://www.siemens.com/ic10

Industry Mall (Online ordering system)

https://mall.industry.siemens.com/mall/en/en/Catalog/product?mlfb=3RW5546-2HA04

Cax online generator

http://support.automation.siemens.com/WW/CAXorder/default.aspx?lang=en&mlfb=3RW5546-2HA04

 $Service \& Support \ (Manuals, \ Certificates, \ Characteristics, \ FAQs, ...)$ 

https://support.industry.siemens.com/cs/ww/en/ps/3RW5546-2HA04

Image database (product images, 2D dimension drawings, 3D models, device circuit diagrams, EPLAN macros, ...) <a href="http://www.automation.siemens.com/bilddb/cax\_de.aspx?mlfb=3RW5546-2HA04&lang=en">http://www.automation.siemens.com/bilddb/cax\_de.aspx?mlfb=3RW5546-2HA04&lang=en</a>

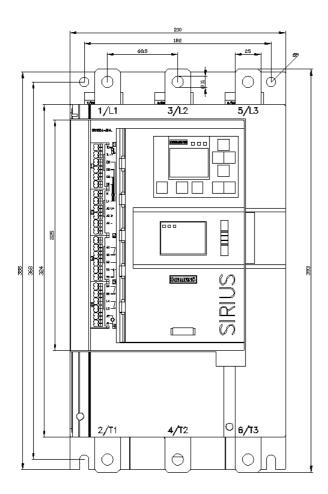
Characteristic: Tripping characteristics, I²t, Let-through current https://support.industry.siemens.com/cs/ww/en/ps/3RW5546-2HA04/char

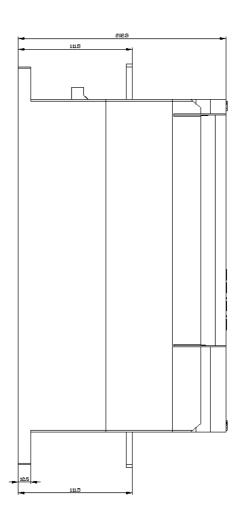
Characteristic: Installation altitude

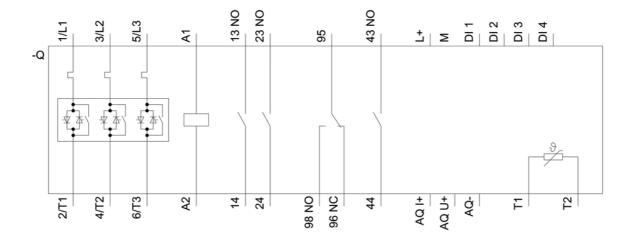
http://www.automation.siemens.com/bilddb/index.aspx?view=Search&mlfb=3RW5546-2HA04&objecttype=14&gridview=view1

Simulation Tool for Soft Starters (STS)

https://support.industry.siemens.com/cs/ww/en/view/101494917







last modified: 3/9/2021 🖸