

## MLFB-Ordering data

#### 6SL3210-1KE18-8AF1



Client order no.: Order no. : Offer no. : Remarks:

Item no.: Consignment no. : Project:

Rated da	ıta
nput	
Number of phases	3 AC
Line voltage	380 480 V +10 % -20 %
Line frequency	47 63 Hz
Rated current (LO)	11.40 A
Rated current (HO)	10.60 A
Output	
Number of phases	3 AC
Rated voltage	400 V
Rated power IEC 400V (LO)	4.00 kW
Rated power NEC 480V (LO)	5.00 hp
Rated power IEC 400V (HO)	3.00 kW
Rated power NEC 480V (HO)	4.00 hp
Rated current (LO)	8.80 A
Rated current (HO)	7.30 A
Rated current (IN)	9.00 A
Max. output current	14.60 A
Pulse frequency	4 kHz
Output frequency for vector control	0 240 Hz
Output frequency for V/f control	0 550 Hz

Overload capability
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## Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

#### High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications			
Power factor λ	0.70 0.85		
Offset factor cos φ	0.95		
Efficiency η	0.97		
Sound pressure level (1m)	52 dB		
Power loss	0.15 kW		
Filter class (integrated)	Class A		

Ambient conditions			
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.005 m³/s (0.177 ft³/s)		
Installation altitude	1000 m (3280.84 ft)		
Ambient temperature			
Operation	-10 40 °C (14 104 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-40 70 °C (-40 158 °F)		
Relative humidity			

#### 95 % At 40 °C (104 °F), condensation Max. operation and icing not permissible

Closed-loop control techniques			
V/f linear / square-law / parameterizable	Yes		
V/f with flux current control (FCC)	Yes		
V/f ECO linear / square-law	Yes		
Sensorless vector control	Yes		
Vector control, with sensor	No		
Encoderless torque control	No		
Torque control, with encoder	No		



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Mechanical	data	Com	munication
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP
Size	FSA	Connections	
Net weight	1.70 kg (3.75 lb)	Signal cable	
Width	73 mm (2.87 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Height	196 mm (7.72 in)	Line side	
Depth	208 mm (8.19 in)	Version	Plug-in screw terminals
Inputs / out	tputs	Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)
Standard digital inputs		Motor end	
Number	6	Version	Plug-in screw terminals
Switching level: 0→1	11 V	Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)
Switching level: 1→0	5 V	DC link (for braking resistor)	
Max. inrush current	15 mA	Version	Plug-in screw terminals
Fail-safe digital inputs		Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)
Number	1	Line length, max.	15 m (49.21 ft)
Digital outputs		PE connection	On housing with M4 screw
Number as relay changeover contact	1	Max. motor cable length	,
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)
Number as transistor	1	Unshielded	150 m (492.13 ft)
Output (resistive load)	DC 30 V, 0.5 A	Standards	
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)		
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC
Switching threshold as digital inp	out		
0→1	4 V		

# Analog outputs

1→0

**Number** 1 (Non-isolated output)

# PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^\circ\text{C}$ 

1.6 V



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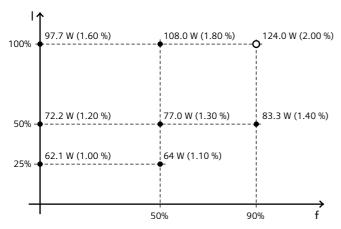
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# Figure similar

## Converter losses to IEC61800-9-2\*

Efficiency class	IE2
Comparison with the reference converter (90% /	33.80 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values