



Figure similar

### MLFB-Ordering data

6SL3210-1KE18-8AB1

Client order no. :

Order no. :

Offer no. :

Remarks :

Item no. :

Consignment no. :

Project :

Rated data		General tech. specifications	
<b>Input</b>		<b>Power factor <math>\lambda</math></b>	0.70 ... 0.85
Number of phases	3 AC	<b>Offset factor <math>\cos \phi</math></b>	0.95
Line voltage	380 ... 480 V +10 % -20 %	<b>Efficiency <math>\eta</math></b>	0.97
Line frequency	47 ... 63 Hz	<b>Sound pressure level (1m)</b>	52 dB
Rated current (LO)	11.40 A	<b>Power loss</b>	0.15 kW
Rated current (HO)	10.60 A	<b>Filter class (integrated)</b>	Class A
<b>Output</b>		<b>Ambient conditions</b>	
Number of phases	3 AC	<b>Cooling</b>	Air cooling using an integrated fan
Rated voltage	400 V	<b>Cooling air requirement</b>	0.005 m <sup>3</sup> /s (0.177 ft <sup>3</sup> /s)
Rated power IEC 400V (LO)	4.00 kW	<b>Installation altitude</b>	1000 m (3280.84 ft)
Rated power NEC 480V (LO)	5.00 hp	<b>Ambient temperature</b>	
Rated power IEC 400V (HO)	3.00 kW	<b>Operation</b>	-10 ... 40 °C (14 ... 104 °F)
Rated power NEC 480V (HO)	4.00 hp	<b>Transport</b>	-40 ... 70 °C (-40 ... 158 °F)
Rated current (LO)	8.80 A	<b>Storage</b>	-40 ... 70 °C (-40 ... 158 °F)
Rated current (HO)	7.30 A	<b>Relative humidity</b>	
Rated current (IN)	9.00 A	<b>Max. operation</b>	95 % At 40 °C (104 °F), condensation and icing not permissible
Max. output current	14.60 A	<b>Closed-loop control techniques</b>	
Pulse frequency	4 kHz	<b>V/f linear / square-law / parameterizable</b>	Yes
Output frequency for vector control	0 ... 240 Hz	<b>V/f with flux current control (FCC)</b>	Yes
Output frequency for V/f control	0 ... 550 Hz	<b>V/f ECO linear / square-law</b>	Yes
<b>Overload capability</b>		<b>Sensorless vector control</b>	Yes
<b>Low Overload (LO)</b>	150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time	<b>Vector control, with sensor</b>	No
<b>High Overload (HO)</b>	200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time	<b>Encoderless torque control</b>	No
		<b>Torque control, with encoder</b>	No



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#### Mechanical data

Degree of protection	IP20 / UL open type
Size	FSA
Net weight	1.70 kg (3.75 lb)
Width	73 mm (2.87 in)
Height	196 mm (7.72 in)
Depth	203 mm (7.99 in)

#### Inputs / outputs

##### Standard digital inputs

Number	6
Switching level: 0→1	11 V
Switching level: 1→0	5 V
Max. inrush current	15 mA

##### Fail-safe digital inputs

Number	1
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##### Digital outputs

Number as relay changeover contact	1
Output (resistive load)	DC 30 V, 0.5 A
Number as transistor	1
Output (resistive load)	DC 30 V, 0.5 A

##### Analog / digital inputs

Number	1 (Differential input)
Resolution	10 bit

##### Switching threshold as digital input

0→1	4 V
1→0	1.6 V

##### Analog outputs

Number	1 (Non-isolated output)
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##### PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5$  °C

#### Communication

Communication	USS/MODBUS RTU
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#### Connections

##### Signal cable

Conductor cross-section	0.15 ... 1.50 mm <sup>2</sup> (AWG 24 ... AWG 16)
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##### Line side

Version	Plug-in screw terminals
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Conductor cross-section	1.00 ... 2.50 mm <sup>2</sup> (AWG 18 ... AWG 14)
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##### Motor end

Version	Plug-in screw terminals
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Conductor cross-section	1.00 ... 2.50 mm <sup>2</sup> (AWG 18 ... AWG 14)
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##### DC link (for braking resistor)

Version	Plug-in screw terminals
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Conductor cross-section	1.00 ... 2.50 mm <sup>2</sup> (AWG 18 ... AWG 14)
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Line length, max.	15 m (49.21 ft)
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PE connection	On housing with M4 screw
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##### Max. motor cable length

Shielded	50 m (164.04 ft)
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Unshielded	150 m (492.13 ft)
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#### Standards

Compliance with standards	UL, cUL, CE, C-Tick (RCM)
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CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC
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Figure similar

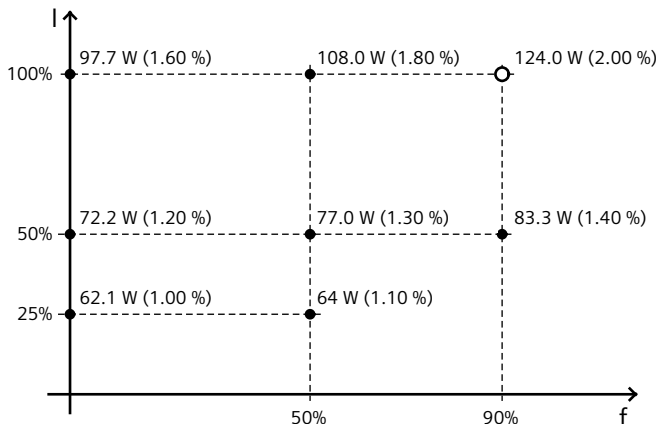
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### Converter losses to IEC61800-9-2\*

Efficiency class IE2

Comparison with the reference converter (90% / 100%) 33.80 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

\*converted values