

# **MLFB-Ordering data**

6SL3210-1KE23-2AP1



Client order no. :Item no. :Order no. :Consignment no. :Offer no. :Project :

Remarks :			
Rated data		General tech. specifications	
Input		Power factor λ	0.70 0.85
Number of phases	3 AC	Offset factor cos φ	0.95
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.97
Line frequency	47 63 Hz	Sound pressure level (1m)	66 dB
Rated current (LO)	40.60 A	Power loss	0.43 kW
Rated current (HO)	36.40 A	Filter class (integrated)	Class A
Output		Ambien	t conditions
Number of phases	3 AC	Ambien	t conditions
Rated voltage	400 V	Cooling	Air cooling using an integrated fan
Rated power IEC 400V (LO)	15.00 kW		0.040 37 (0.036 (37)
Rated power NEC 480V (LO)	20.00 hp	Cooling air requirement	0.018 m³/s (0.636 ft³/s)
Rated power IEC 400V (HO)	11.00 kW	Installation altitude	1000 m (3280.84 ft)
Rated power NEC 480V (HO)	15.00 hp	Ambient temperature	
Rated current (LO)	31.00 A	Operation	-10 40 °C (14 104 °F)
Rated current (HO)	25.00 A	Transport	-40 70 °C (-40 158 °F)
Rated current (IN)	32.00 A	Storage	-40 70 °C (-40 158 °F)
Max. output current	50.00 A	Relative humidity	
Pulse frequency	4 kHz	Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible
Output frequency for vector control	0 240 Hz		
	3 III 2 13 112	Closed-loop control techniques	
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / parameterizable Yes	
		V/f with flux current control (FC	C) Yes
Overload capability		V/f ECO linear / square-law	Yes
Low Overload (LO)		Sensorless vector control	Yes

 $150\ \%$  base load current IL for 3 s, followed by  $110\ \%$  base load current IL for 57 s in a  $300\ s$  cycle time

### High Overload (HO)

 $200\,\%$  base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

No

No

No

Vector control, with sensor

**Encoderless torque control** 

Torque control, with encoder



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Mechanical data		Communication	
Degree of protection	IP20 / UL open type	Communication	PROFIBUS DP
Size	FSC	Connections	
Net weight	4.40 kg (9.70 lb)	Signal cable	
Width	140 mm (5.51 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Height	295 mm (11.61 in)	Line side	
Depth	203 mm (7.99 in)	Version	Plug-in screw terminals
Inputs / outputs		Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6)
Standard digital inputs		Motor end	
Number	6	Version	Plug-in screw terminals
Switching level: 0→1	11 V	Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6)
Switching level: 1→0	5 V	DC link (for braking resistor)	
Max. inrush current	15 mA	Version	Plug-in screw terminals
Fail-safe digital inputs		Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6)
Number	1	Line length, max.	15 m (49.21 ft)
Digital outputs			
Number as relay changeover contact	1	PE connection  Max. motor cable length	On housing with M4 screw
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)
Number as transistor	1	Unshielded	150 m (492.13 ft)
Output (resistive load)	DC 30 V, 0.5 A	Standards	
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)		
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC
Switching threshold as digital input			
0→1	4 V		

**Analog outputs** 

1 → 0

1 (Non-isolated output) Number

# PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^\circ\text{C}$ 

1.6 V



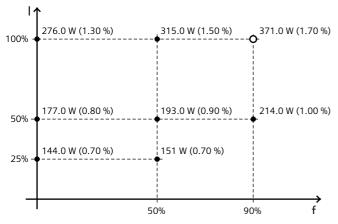
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Figure similar

### Converter losses to IEC61800-9-2\*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	34.20 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values