

MLFB-Ordering data

6SL3210-1KE23-2UB1



Client order no. : Item no. :
Order no. : Consignment no. :
Offer no. : Project :
Remarks :

Rated data		General tech. specifications	
Input		Power factor λ	0.70 0.85
Number of phases	3 AC	Offset factor cos φ	0.95
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.97
Line frequency	47 63 Hz	Sound pressure level (1m)	66 dB
Rated current (LO)	40.60 A	Power loss	0.43 kW
Rated current (HO)	36.40 A	Filter class (integrated)	Unfiltered
Output		-	
Number of phases	3 AC	Ambient conditions	
Rated voltage	400 V	Cooling	Air cooling using an integrated fan
Rated power IEC 400V (LO)	15.00 kW	Coding to the second	0.040 31 (0.036(31)
Rated power NEC 480V (LO)	20.00 hp	Cooling air requirement	0.018 m³/s (0.636 ft³/s)
Rated power IEC 400V (HO)	11.00 kW	Installation altitude	1000 m (3280.84 ft)
Rated power NEC 480V (HO)	15.00 hp	Ambient temperature	
Rated current (LO)	31.00 A	Operation	-10 40 °C (14 104 °F)
Rated current (HO)	25.00 A	Transport	-40 70 °C (-40 158 °F)
Rated current (IN)	32.00 A	Storage	-40 70 °C (-40 158 °F)
Max. output current	50.00 A	Relative humidity	
Pulse frequency	4 kHz	Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible
Output frequency for vector control	0 240 Hz		
		Closed-loop	control techniques
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / parameterizable Yes	
		V/f with flux current control (Fo	CC) Yes
Overload capability		V/f ECO linear / square-law	Yes
Low Overload (LO)		Sensorless vector control	Yes
150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a		Vector control, with sensor	No

High Overload (HO)

300 s cycle time

 $200\,\%$ base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

No

No

Encoderless torque control

Torque control, with encoder



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Mechanical data		Communication	
IP20 / UL open type	Communication	USS/MODBUS RTU	
FSC	Connections		
4.40 kg (9.70 lb)	Signal cable		
140 mm (5.51 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)	
295 mm (11.61 in)	Line side		
203 mm (7.99 in)	Version	Plug-in screw terminals	
Inputs / outputs		6.00 16.00 mm² (AWG 10 AWG 6)	
	Motor end		
6	Version	Plug-in screw terminals	
11 V	Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6)	
5 V	DC link (for braking resistor))	
15 mA	Version	Plug-in screw terminals	
	Conductor cross-section	6.00 16.00 mm ² (AWG 10 AWG 6)	
1	Line length, max.	15 m (49.21 ft)	
	-	On housing with M4 screw	
1	Max. motor cable length	on nousing with wire screw	
DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)	
1	Unshielded	150 m (492.13 ft)	
DC 30 V, 0.5 A	Standards		
	Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
1 (Differential input)			
10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC	
put			
4 V			
	IP20 / UL open type FSC 4.40 kg (9.70 lb) 140 mm (5.51 in) 295 mm (11.61 in) 203 mm (7.99 in) tputs 6 11 V 5 V 15 mA 1 DC 30 V, 0.5 A 1 (Differential input) 10 bit put	IP20 / UL open type FSC 4.40 kg (9.70 lb) Signal cable Conductor cross-section Line side Version Conductor cross-section Motor end Version Conductor cross-section DC link (for braking resistor Tonductor cross-section Line length, max. PE connection Max. motor cable length DC 30 V, 0.5 A Shielded Unshielded DC 30 V, 0.5 A Compliance with standards 1 (Differential input) 10 bit CC Conductor cross-section Conductor cross-section Line length, max. PE connection Max. motor cable length Compliance with standards CE marking	

Analog outputs

1→0

Number 1 (Non-isolated output)

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

1.6 V



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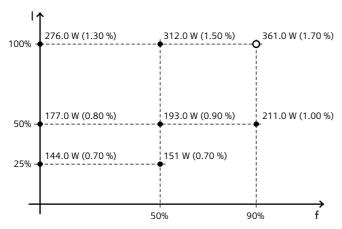
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Figure similar

Converter losses to IEC61800-9-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	33.30 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values