

## **MLFB-Ordering data**

6SL3210-1KE21-3UF1



Figure similar

Client order no. : Order no. : Offer no. : Remarks :

ltem no. :
Consignment no. :
Project :

Rated data		General tech. specifications			
Input		Power factor λ	0.	70 0.85	
Number of phases	3 AC	Offset factor cos φ	0.	95	
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.	97	
Line frequency	47 63 Hz	Sound pressure level (1m)	63	3 dB	
Rated current (LO)	16.50 A	Power loss	0.	18 kW	
Rated current (HO)	12.80 A	Filter class (integrated)	Ur	nfiltered	
Output		-			
Number of phases	3 AC	Ambient conditions			
Rated voltage	400 V	Cooling	Air coolii	ng using an integrated fan	
Rated power IEC 400V (LO)	5.50 kW				
Rated power NEC 480V (LO)	7.50 hp	Cooling air requirement	0.009 m	<sup>3</sup> /s (0.318 ft <sup>3</sup> /s)	
Rated power IEC 400V (HO)	4.00 kW	Installation altitude	1000 m	(3280.84 ft)	
Rated power NEC 480V (HO)	5.00 hp	Ambient temperature			
Rated current (LO)	12.50 A	Operation	-10 40	) °C (14 104 °F)	
Rated current (HO)	8.80 A	Transport	-40 70	) °C (-40 158 °F)	
Rated current (IN)	13.00 A	Storage	-40 70	) °C (-40 158 °F)	
Max. output current	17.60 A	Relative humidity			
Pulse frequency	4 kHz			95 % At 40 °C (104 °F), condensation and icing not permissible	
ruise nequency	4 KHZ	Max. operation			
Output frequency for vector control	0 240 Hz	Closed-loop control techniques			
Output frequency for V/f control	0 550 Hz	· · ·			
		V/f linear / square-law / parame	eterizable	Yes	
		V/f with flux current control (FC	CC)	Yes	
Overload capability		V/f ECO linear / square-law		Yes	

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

#### High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No



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Mechanical data		Figure sim		
Degree of protection IP20 / UL open type		Communication	PROFINET, EtherNet/IP	
Size	FSB	Connections		
Net weight	2.30 kg (5.07 lb)	Signal cable		
Width	100 mm (3.94 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16	
Height	196 mm (7.72 in)	Line side		
Depth	208 mm (8.19 in)	Version	Plug-in screw terminals	
Inputs / out	puts	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10	
tandard digital inputs		Motor end		
Number	6	Version	Plug-in screw terminals	
Switching level: 0→1	11 V	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10	
Switching level: 1→0	5 V	DC link (for braking resistor)	)	
Max. inrush current	15 mA	Version	Plug-in screw terminals	
ail-safe digital inputs		Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10	
Number	1	Line length, max.	15 m (49.21 ft)	
igital outputs		PE connection	On housing with M4 screw	
Number as relay changeover contact	1	Max. motor cable length		
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)	
Number as transistor	1	Unshielded	150 m (492.13 ft)	
Output (resistive load)	DC 30 V, 0.5 A	Standards		
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)			
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Volta Directive 2006/95/EC	
witching threshold as digital in	put			
0→1	4 V			
1→0	1.6 V			
analog outputs				
Number	1 (Non-isolated output)			
PTC/ KTY interface				

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^\circ\mathrm{C}$ 



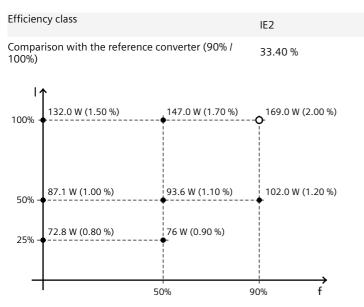
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Figure similar

Converter losses to IEC61800-9-2\*



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values