

### MLFB-Ordering data

6SL3210-1KE17-5UF1



Client order no. :		
Order no. :		
Offer no. :		
Remarks :		

Rated data	
narks :	
er no. :	Project :
er no. :	Consignment no. :
nt order no. :	Item no. :

Rated data			
Input			
Number of phases	3 AC		
Line voltage	380 480 V +10 % -20 %		
Line frequency	47 63 Hz		
Rated current (LO)	9.50 A		
Rated current (HO)	8.20 A		
Output			
Number of phases	3 AC		
Rated voltage	400 V		
Rated power IEC 400V (LO)	3.00 kW		
Rated power NEC 480V (LO)	4.00 hp		
Rated power IEC 400V (HO)	2.20 kW		
Rated power NEC 480V (HO)	3.00 hp		
Rated current (LO)	7.30 A		
Rated current (HO)	5.60 A		
Rated current (IN)	7.50 A		
Max. output current	11.20 A		
Pulse frequency	4 kHz		
Output frequency for vector control	0 240 Hz		
Output frequency for V/f control	0 550 Hz		

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# Overload capability

### Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

#### High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor cos φ	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	52 dB	
Power loss	0.14 kW	
Filter class (integrated)	Unfiltered	

Ambient conditions			
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.005 m³/s (0.177 ft³/s)		
Installation altitude	1000 m (3280.84 ft)		
Ambient temperature			
Operation	-10 40 °C (14 104 °F)		
<b>Transport</b> -40 70 °C (-40 158 °F)			
Storage	-40 70 °C (-40 158 °F)		
Relative humidity			

Closed-loop control tec	hniques
V/f linear / square-law / parameterizable	Yes
V/f with flux current control (FCC)	Yes
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No

95 % At 40 °C (104 °F), condensation

and icing not permissible

Max. operation



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		1	Figu	
Mechanical data		Com	Communication	
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP	
Size	FSA	Connections		
Net weight	1.70 kg (3.75 lb)	Signal cable		
Width	73 mm (2.87 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWC	
Height	196 mm (7.72 in)	Line side		
Depth	208 mm (8.19 in)	Version	Plug-in screw terminals	
Inputs / ou	tputs	Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG	
tandard digital inputs		Motor end		
Number	6	Version	Plug-in screw terminals	
Switching level: 0→1	11 V	Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG	
Switching level: 1→0	5 V	DC link (for braking resistor)	)	
Max. inrush current	15 mA	Version	Plug-in screw terminals	
ail-safe digital inputs		Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG	
Number	1	Line length, max.	15 m (49.21 ft)	
igital outputs				
Number as relay changeover contact	1	PE connection  Max. motor cable length	On housing with M4 screw	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)	
Number as transistor	1	Unshielded	150 m (492.13 ft)	
Output (resistive load)	DC 30 V, 0.5 A	Standards		
nalog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)		, , , , , ,	
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-V Directive 2006/95/EC	
witching threshold as digital in	put			
0→1	4 V			
1→0	1.6 V			

# PTC/ KTY interface

**Analog outputs** 

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^\circ\text{C}$ 

1 (Non-isolated output)



### **MLFB-Ordering data**

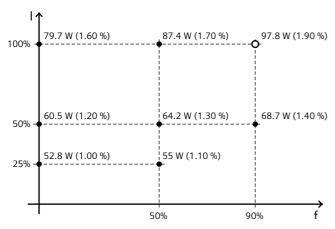
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Figure similar

# Converter losses to IEC61800-9-2\*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	30.30 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values