

### MLFB-Ordering data

6SL3210-1KE21-7UF1



Client order no. : Order no. : Offer no. : Remarks:

Item no.: Consignment no. : Project :

Rated da	ıta	
Input		P
Number of phases	3 AC	c
Line voltage	380 480 V +10 % -20 %	E
Line frequency	47 63 Hz	S
Rated current (LO)	21.50 A	P
Rated current (HO)	18.20 A	F
Output		
Number of phases	3 AC	
Rated voltage	400 V	c
Rated power IEC 400V (LO)	7.50 kW	
Rated power NEC 480V (LO)	10.00 hp	C
Rated power IEC 400V (HO)	5.50 kW	li
Rated power NEC 480V (HO)	7.50 hp	An
Rated current (LO)	16.50 A	C
Rated current (HO)	12.50 A	T
Rated current (IN)	17.00 A	S
Max. output current	25.00 A	Re
Pulse frequency	4 kHz	N
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	\

Overload capability		
Low Overload (LO)		

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

### High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor cos φ	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	63 dB	
Power loss	0.24 kW	
Filter class (integrated)	Unfiltered	

Ambient conditions		
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.009 m³/s (0.318 ft³/s)	
Installation altitude	1000 m (3280.84 ft)	
Ambient temperature		
Operation	-10 40 °C (14 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



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Mechanical data		Com	Communication	
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP	
Size	FSB	Connections		
Net weight	2.30 kg (5.07 lb)	Signal cable		
Width	100 mm (3.94 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)	
Height	196 mm (7.72 in)	Line side		
Depth	208 mm (8.19 in)	Version	Plug-in screw terminals	
Inputs / ou	tputs	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)	
Standard digital inputs		Motor end		
Number	6	Version	Plug-in screw terminals	
Switching level: 0→1	11 V	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)	
Switching level: 1→0	5 V	DC link (for braking resistor	)	
Max. inrush current	15 mA	Version	Plug-in screw terminals	
Fail-safe digital inputs		Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)	
Number	1	Line length, max.	15 m (49.21 ft)	
Digital outputs		PE connection	On housing with M4 screw	
Number as relay changeover contact	1	Max. motor cable length	chineasing that in residu	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)	
Number as transistor	1	Unshielded	150 m (492.13 ft)	
Output (resistive load)	DC 30 V, 0.5 A	Standards		
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)			
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC	
Switching threshold as digital in	put			
0→1	4 V			
1→0	1.6 V			

# Number

PTC/ KTY interface

**Analog outputs** 

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5\,^{\circ}\text{C}$ 

1 (Non-isolated output)



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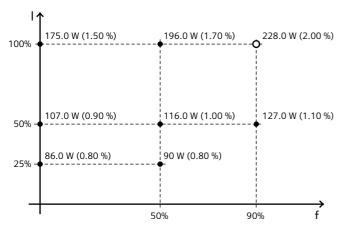
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#### Figure similar

## Converter losses to IEC61800-9-2\*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	36.70 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values