

# MLFB-Ordering data

## 6SL3210-1KE26-0AF1



Client order no. : Order no. : Offer no. : Remarks : Item no. : Consignment no. : Project :

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 % -20 %	
Line frequency	47 63 Hz	
Rated current (LO)	53.00 A	
Rated current (HO)	44.00 A	
Output		
Number of phases	3 AC	
Rated voltage	400 V	
Rated power IEC 400V (LO)	30.00 kW	
Rated power NEC 480V (LO)	30.00 hp	
Rated power IEC 400V (HO)	22.00 kW	
Rated power NEC 480V (HO)	25.00 hp	
Rated current (LO)	58.00 A	
Rated current (HO)	43.00 A	
Rated current (IN)	58.00 A	
Max. output current	87.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

Overload capability	load capability
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## Low Overload (LO)

 $150\ \%$  base load current IL for 3 s, followed by  $110\ \%$  base load current IL for 57 s in a  $300\ s$  cycle time

#### High Overload (HO)

 $200\,\%$  base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
	0.00	
Power factor λ	0.90 0.95	
Offset factor cos φ	0.99	
Efficiency η	0.98	
Sound pressure level (1m)	72 dB	
Power loss	0.77 kW	
Filter class (integrated)	Class A	

Ambient conditions		
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.055 m³/s (1.942 ft³/s)	
Installation altitude	1000 m (3280.84 ft)	
Ambient temperature		
Operation	-20 40 °C (-4 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		

Closed-loop control techniques			
V/f linear / square-law / parameterizable	Yes		
V/f with flux current control (FCC)	Yes		
V/f ECO linear / square-law	Yes		
Sensorless vector control	Yes		
Vector control, with sensor	No		
Encoderless torque control	No		
Torque control, with encoder	No		

95 % RH, condensation not permitted

Max. operation



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			Figure similar
Mechanical data		Communication	
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP
Size	FSD	Connections	
Net weight	18.80 kg (41.45 lb)	Signal cable	
Width	200 mm (7.87 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Height	472 mm (18.58 in)	Line side	
Depth	237 mm (9.33 in)	Version	screw-type terminal
Inputs / out	puts	Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG 2)
Standard digital inputs		Motor end	
Number	6	Version	Screw-type terminals
Switching level: 0→1	11 V	Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG 2)
Switching level: 1→0	5 V	DC link (for braking resistor)	
Max. inrush current	15 mA	Version	Screw-type terminals
Fail-safe digital inputs		Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG 2)
Number	1	Line length, max.	10 m (32.81 ft)
Digital outputs		PE connection	Screw-type terminals
Number as relay changeover contact	1	Max. motor cable length	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	200 m (656.17 ft)
Number as transistor	1	Unshielded	300 m (984.25 ft)
Output (resistive load)	DC 30 V, 0.5 A	S	tandards
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)		
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC
Switching threshold as digital in	out		
0→1	4 V		
1→0	1.6 V		
Analog outputs			
Number	1 (Non-isolated output)		
PTC/ KTY interface			

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^\circ\text{C}$ 

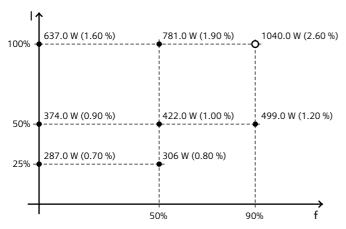


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## Converter losses to IEC61800-9-2\*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	54.10 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values