SIEMENS

Data sheet



SIPLUS S7-1200 CPU 1214C DC/DC/DC for medial exposure with conformal coating based on 6ES7214-1AG40-0XB0 . compact CPU, DC/DC/DC, onboard I/O: 14 DI 24 V DC 10 DO 24 V DC 2 AI 0-10 V DC, Power supply: DC 20.4-28.8V DC, Program/data memory 100 KB

Figure similar

Product type designation	CPU 1214C DC/DC/DC
Supply voltage	
Rated value (DC)	
• 24 V DC	Yes
permissible range, lower limit (DC)	20.4 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Load voltage L+	
 Rated value (DC) 	24 V
 permissible range, lower limit (DC) 	20.4 V
 permissible range, upper limit (DC) 	28.8 V
Input current	
Current consumption (rated value)	500 mA; CPU only
Current consumption, max.	1 500 mA; CPU with all expansion modules
Inrush current, max.	12 A; at 28.8 V DC
Output current	
for backplane bus (5 V DC), max.	1 600 mA; Max. 5 V DC for SM and CM
Encoder supply	
24 V encoder supply	
• 24 V	L+ minus 4 V DC min.
Power loss	
Power loss, typ.	12 W
Memory	
Work memory	
integrated	100 kbyte
expandable	No
Load memory	
integrated	4 Mbyte
Plug-in (SIMATIC Memory Card), max.	with SIMATIC memory card
Backup	
• present	Yes; maintenance-free
without battery	Yes
CPU processing times	
for bit operations, typ.	0.085 μs; / instruction
for word operations, typ.	1.7 µs; / instruction

for floating point arithmetic, typ. CPU-blocks Number of blocks (total) DBs, FCs, FBs, counters and timers. The maximum number of addressable blocks ranges from 1 to 65535. There is no restriction entire working memory can be used Number, max. Limited only by RAM for code Number, max. Limited only by RAM for code Size, max. Local data Size, max. Local data Per priority class, max. Local data In purple, adjustable Outputs, adjustable Outputs, adjustable Address area Process image Inputs, adjustable Outputs, adjustable Address area Process image Inputs, adjustable Outputs, adjustable Address area Process image Inputs, adjustable Outputs, adjustable Outputs, adjustable Address area Process image Inputs, adjustable Outputs, adjustable Outputs, adjustable Address area Process image Inputs, adjustable Outputs, adjustable Outputs, adjustable Outputs, adjustable Outputs, adjustable I kbyte Hardware configuration Number of modules per system, max. Time of day Clock Hardware clock (real-time) Backup time Backup time Outputs usable for technological functions Source/sink input Number of simultaneously controllable inputs all mounting positions — up to 40 °C, max. 14	
Number of blocks (total) DBs, FCs, FBs, counters and timers. The maximum number of addressable blocks ranges from 1 to 65535. There is no restriction entire working memory can be used DBs Number, max. Limited only by RAM for code Limited areas and their retentivity Retentive data area (incl. timers, counters, flags), max. Flag Size, max. Local data per priority class, max. Local data per priority class, max. Local data process image Inputs, adjustable Outputs, adjustable Outputs, adjustable Hardware configuration Number of modules per system, max. Time of day Clock Hardware clock (real-time) Backup time Deviation per day, max. Digital inputs Number of digital inputs Number of digital inputs Number of signultaneously controllable inputs all mounting positions	
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Retentive data area (incl. timers, counters, flags), max. Flag • Size, max. Local data • per priority class, max. Address area Process image • Inputs, adjustable • Outputs, adjustable • Tkbyte • Outputs, adjustable • Hardware configuration Number of modules per system, max. Time of day Clock • Hardware clock (real-time) • Backup time • Deviation per day, max. Digital inputs Number of digital inputs • of which inputs usable for technological functions Source/sink input Number of simultaneously controllable inputs all mounting positions	26: 6
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Flag ● Size, max. Local data ● per priority class, max. Address area Process image ● Inputs, adjustable ● Outputs, adjustable ● Outputs, adjustable I kbyte ● Outputs, adjustable Hardware configuration Number of modules per system, max. 3 comm. modules, 1 signal board, 8 signal modules Time of day Clock ● Hardware clock (real-time) ● Backup time ● Deviation per day, max. Digital inputs Number of digital inputs ● of which inputs usable for technological functions Source/sink input Number of simultaneously controllable inputs all mounting positions	26: 6
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Source/sink input Yes Number of simultaneously controllable inputs all mounting positions	
Number of simultaneously controllable inputs all mounting positions	
all mounting positions	
Input voltage	
• Rated value (DC) 24 V	
• for signal "0" 5 V DC at 1 mA	
• for signal "1" 15 V DC at 2.5 mA	
Input delay (for rated value of input voltage)	
for standard inputs	
— parameterizable 0.2 ms, 0.4 ms, 0.8 ms, 1.6 ms, 3.2 ms, 6.4 ms and 12.8 ms, selection	able
in groups of four	
— at "0" to "1", min. 0.2 ms	
— at "0" to "1", max.	
for interrupt inputs	
— parameterizable Yes	
for technological functions	
— parameterizable Single phase: 3 @ 100 kHz & 3 @ 30 kHz, differential: 3 @ 80 kHz	& 3
@ 30 kHz	
Cable length	
• shielded, max. 500 m; 50 m for technological functions	
• unshielded, max. 300 m; for technological functions: No	
Digital outputs	
Number of digital outputs 10	
of which high-speed outputs 4; 100 kHz Pulse Train Output	
Limitation of inductive shutdown voltage to L+ (-48 V)	
Switching capacity of the outputs	
• with resistive load, max. 0.5 A	
• on lamp load, max. 5 W	
● on lamp load, max. 5 W Output voltage	

- for circual HAII pain	20.1/
• for signal "1", min.	20 V
Output current	0.5.4
• for signal "1" rated value	0.5 A 0.1 mA
for signal "0" residual current, max.	U.I MA
Output delay with resistive load	
• "0" to "1", max.	1 µs
• "1" to "0", max.	5 μs
Switching frequency	
of the pulse outputs, with resistive load, max.	100 kHz
Relay outputs	
Number of relay outputs	0
Cable length	
shielded, max.	500 m
• unshielded, max.	150 m
Analog inputs	
Number of analog inputs	2
Input ranges	
Voltage	Yes
Input ranges (rated values), voltages	
• 0 to +10 V	Yes
— Input resistance (0 to 10 V)	≥100k ohms
Cable length	
• shielded, max.	100 m; twisted and shielded
Analog outputs	
Number of analog outputs	0
Analog value generation for the inputs	
Integration and conversion time/resolution per channel	
Resolution with overrange (bit including sign), max.	10 bit
Integration time, parameterizable	Yes
Conversion time (per channel)	625 µs
Encoder	020 μ3
Connectable encoders	
2-wire sensor	Yes
	Tes
1. Interface	
Interface type	PROFINET
Isolated	Yes
automatic detection of transmission rate	Yes
Autonegotiation	Yes
Autocrossing	Yes
Interface types	
• RJ 45 (Ethernet)	Yes
Protocols	
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
Open IE communication	Yes
Web server	Yes
PROFINET IO Controller	
Transmission rate, max.	100 Mbit/s
Services	
Number of connectable IO Devices, max.	16
PROFINET IO Device	
Services	
— Shared device	Yes
 Number of IO Controllers with shared device, 	2
max.	
Protocols	
Supports protocol for PROFINET IO	Yes
PROFIBUS	Yes; CM 1243-5 required

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AS-Interface	Yes
Protocols (Ethernet)	Voc
TCP/IP Open IF communication	Yes
Open IE communication • TCP/IP	Von
	Yes
• ISO-on-TCP (RFC1006)	Yes
• UDP	Yes
Web server	V
• supported	Yes
User-defined websites Further protocols	Yes
Further protocols • MODBUS	Von
	Yes
Communication functions	
S7 communication	V
• supported	Yes
• as server	Yes
as client	Yes
Number of connections	4C; dynamically
• overall	16; dynamically
Test commissioning functions	
Status/control	
Status/control variable	Yes
• Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
Forcing	V
• Forcing	Yes
Diagnostic buffer	V
• present	Yes
Traces	O. Ha to E40 I/D of data now to a constitution
Number of configurable Traces	2; Up to 512 KB of data per trace are possible
Integrated Functions	
Counter	
Counter • Number of counters	6
Counter • Number of counters • Counting frequency, max.	100 kHz
Counter • Number of counters • Counting frequency, max. Frequency measurement	100 kHz Yes
Counter • Number of counters • Counting frequency, max. Frequency measurement controlled positioning	100 kHz Yes Yes
Counter • Number of counters • Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max.	100 kHz Yes Yes
Counter • Number of counters • Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface	100 kHz Yes Yes 8 4; With integrated DO
Counter • Number of counters • Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller	Yes Yes Yes 8 4; With integrated DO Yes
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs	Yes Yes 8 4; With integrated DO Yes
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs	Yes Yes 4 4
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse)	Yes Yes 8 4; With integrated DO Yes
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation	Yes Yes 4 4
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs	Yes Yes 8 4; With integrated DO Yes 4 100 kHz
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs	Yes Yes 8 4; With integrated DO Yes 4 100 kHz
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs between the channels, in groups of	Yes Yes 8 4; With integrated DO Yes 4 100 kHz
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs between the channels, in groups of	100 kHz Yes Yes 8 4; With integrated DO Yes 4 4 100 kHz
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs Potential separation digital outputs Potential separation digital outputs Potential separation digital outputs Potential separation digital outputs	Yes Yes Yes 8 4; With integrated DO Yes 4 4 100 kHz 500V AC for 1 minute 1
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs Determined between the channels, in groups of Potential separation digital outputs Potential separation digital outputs Determined between the channels	Yes Yes 8 4; With integrated DO Yes 4 100 kHz 500V AC for 1 minute 1 Yes No
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs Potential separation digital outputs	Yes Yes Yes 8 4; With integrated DO Yes 4 4 100 kHz 500V AC for 1 minute 1
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs Potential separation digital outputs	Yes Yes 8 4; With integrated DO Yes 4 100 kHz 500V AC for 1 minute 1 Yes No
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs Potential separation digital outputs Potential separation digital outputs Potential separation digital outputs between the channels, in groups of EMC Interference immunity against discharge of static electricity	Yes Yes 8 4; With integrated DO Yes 4 100 kHz 500V AC for 1 minute 1 Yes No 1
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs Potential separation digital outputs	Yes Yes 8 4; With integrated DO Yes 4 100 kHz
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs Potential separation digital outputs Interference immunity against discharge of static electricity Interference immunity against discharge of static	Yes Yes 8 4; With integrated DO Yes 4 100 kHz 500V AC for 1 minute 1 Yes No 1
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs Potential separation digital outputs Potential separation digital outputs between the channels, in groups of Potential separation digital outputs Potential separation digital outputs Interference immunity against discharge of static electricity Interference immunity against discharge of static electricity acc. to IEC 61000-4-2	Yes Yes 8 4; With integrated DO Yes 4 100 kHz 500V AC for 1 minute 1 Yes No 1
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs Potential separation digital outputs Potential separation digital outputs Potential separation digital outputs Potential separation digital outputs Interference immunity against discharge of static electricity Interference immunity against discharge Test voltage at air discharge Interference immunity to cable-borne interference	100 kHz Yes Yes 8 4; With integrated DO Yes 4 4 100 kHz 500V AC for 1 minute 1 Yes No 1
Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs Potential separation digital outputs Potential separation digital inputs Potential separation digital inpu	Yes Yes Yes 8 4; With integrated DO Yes 4 100 kHz 500V AC for 1 minute 1 Yes No 1

 Interference immunity on signal cables acc. to IEC 61000-4-4 	Yes
Interference immunity against voltage surge	
Interference immunity on supply lines acc. to IEC	Yes
61000-4-5	1.00
Interference immunity against conducted variable disturbance	e induced by high-frequency fields
 Interference immunity against high-frequency radiation acc. to IEC 61000-4-6 	Yes
Emission of radio interference acc. to EN 55 011	
 Limit class A, for use in industrial areas 	Yes; Group 1
 Limit class B, for use in residential areas 	Yes; When appropriate measures are used to ensure compliance with the limits for Class B according to EN 55011
Degree and class of protection	
IP degree of protection	IP20
Ambient conditions	
Free fall	
• Fall height, max.	0.3 m; five times, in product package
Ambient temperature during operation	, , , , , , , , , , , , , , , , , , , ,
• min.	-20 °C; = Tmin; Startup @ 0 °C
• max.	60 °C; Number of simultaneously activated inputs or outputs 7 or 5 (no adjacent points) at 60 °C horizontal or 50 °C vertical, 14 or 10 at 55 °C horizontal or 45 °C vertical
 horizontal installation, min. 	-20 °C; = Tmin (incl. condensation/frost); start-up @ 0 °C
 horizontal installation, max. 	60 °C; = Tmax
 vertical installation, min. 	-20 °C; = Tmin; Startup @ 0 °C
 vertical installation, max. 	50 °C; = Tmax
 At cold restart, min. 	0 °C
Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Altitude during operation relating to sea level	
 Installation altitude above sea level, max. 	5 000 m
Ambient air temperature-barometric pressure- altitude	Tmin Tmax at 1 140 hPa 795 hPa (-1 000 m +2 000 m) // Tmin (Tmax - 10 K) at 795 hPa 658 hPa (+2 000 m +3 500 m) // Tmin (Tmax -20 K) at 658 hPa 540 hPa (+3 500 m +5 000 m)
Relative humidity	
With condensation, tested in accordance with IEC 60068-2-38, max.	100 %; RH incl. condensation/frost (no commissioning under condensation conditions)
Vibrations	·
 Vibration resistance during operation acc. to IEC 60068-2-6 	2 g (m/s²) wall mounting, 1 g (m/s²) DIN rail
 Operation, tested according to IEC 60068-2-6 	Yes
Shock testing	
• tested according to IEC 60068-2-27	Yes; IEC 68, Part 2-27 half-sine: strength of the shock 15 g (peak value), duration 11 ms
Resistance	
Coolants and lubricants	
Resistant to commercially available coolants and lubricants	Yes; Incl. diesel and oil droplets in the air
Use in stationary industrial systems	
— to biologically active substances according to EN 60721-3-3	Yes; Class 3B2 mold, fungus and dry rot spores (with the exception of fauna); Class 3B3 on request
— to chemically active substances according to EN 60721-3-3	Yes; Class 3C4 (RH < 75 %) incl. salt spray acc. to EN 60068-2-52 (severity degree 3); *
— to mechanically active substances according to EN 60721-3-3	Yes; Class 3S4 incl. sand, dust, *
Use on ships/at sea	
— to biologically active substances according to EN 60721-3-6	Yes; Class 6B2 mold and fungal spores (excluding fauna); Class 6B3 on request
 to chemically active substances according to EN 60721-3-6 	Yes; Class 6C3 (RH < 75 %) incl. salt spray acc. to EN 60068-2-52 (severity degree 3); *
 to mechanically active substances according to 	Yes; Class 6S3 incl. sand, dust; *

EN 60721-3-6	
Usage in industrial process technology	
 Against chemically active substances acc. to EN 60654-4 	Yes; Class 3 (excluding trichlorethylene)
 Environmental conditions for process, measuring and control systems acc. to ANSI/ISA- 71.04 	Yes; Level GX group A/B (excluding trichlorethylene; harmful gas concentrations up to the limits of EN 60721-3-3 class 3C4 permissible); level LC3 (salt spray) and level LB3 (oil)
Remark	
 Note regarding classification of environmental conditions acc. to EN 60721, EN 60654-4 and ANSI/ISA-71.04 	* The supplied plug covers must remain in place over the unused interfaces during operation!
Conformal coating	
 Coatings for printed circuit board assemblies acc. to EN 61086 	Yes; Class 2 for high reliability
 Protection against fouling acc. to EN 60664-3 	Yes; Type 1 protection
 Military testing according to MIL-I-46058C, Amendment 7 	Yes; Discoloration of coating possible during service life
 Qualification and Performance of Electrical Insulating Compound for Printed Board Assemblies according to IPC-CC-830A 	Yes; Conformal coating, Class A
Configuration	
Programming	
Programming language	
— LAD	Yes
— FBD	Yes
— SCL	Yes
Cycle time monitoring	
adjustable	Yes
Dimensions	
Width	110 mm
Height	100 mm
Depth	75 mm
Weights	
Weight, approx.	415 g

last modified:

3/2/2021